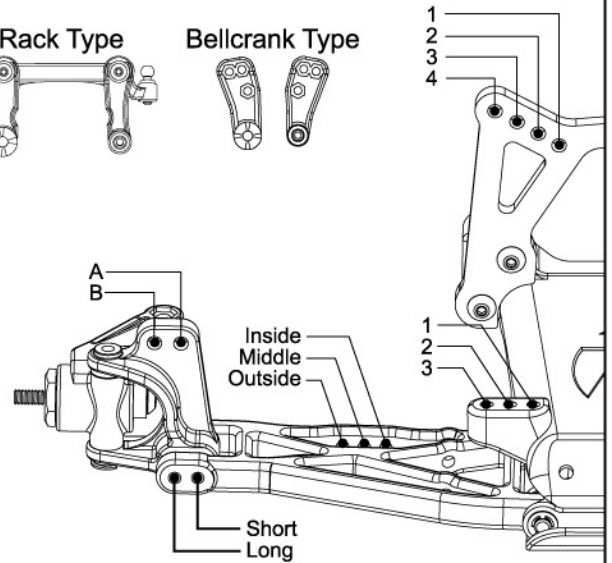
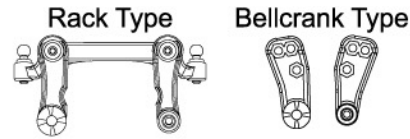


# TENLOS SETUP SHEET XXX CR

Name: Brian Preddy Date: 29 March 2009 Event: \_\_\_\_\_  
 City: \_\_\_\_\_ State: \_\_\_\_\_ Track: Stofford  
 Track  Indoor  Tight  Smooth  Hard Packed  Blue Groove  Wet  Low Bite  High Bite  
 Conditions  Outdoor  Open  Rough  Loose/Loamy  Dry  Dusty  Med Bite  Other \_\_\_\_\_

## Front Suspension

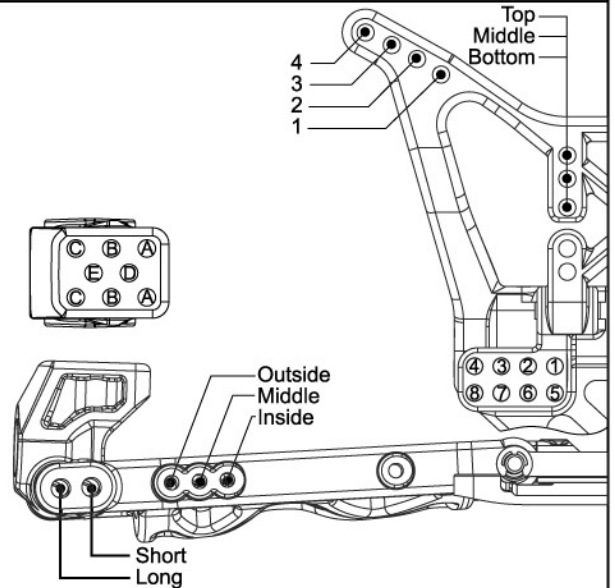
Toe: 0 degree  
 Ride Height: 23mm  
 Camber: -1 degree  
 Caster: 30 degree  
 Sway Bar: None  
 Oil: 37.5 wt  
 Piston: Red (56) Other: \_\_\_\_\_  
 Spring: Green 3.5 - No Coils cut  
 Limiters: None (Inside and Outside)  
 Spindle Height: Low  
 Axle Spacer: Narrow  
 Steering Type: Rack  
 Bump Steer: None Ackerman washers: None  
 Camber Link: 2 - B Ballstud washers: 006  
 Shock Location: 3 - Middle  
 VLA: Short  
 Front Wing: None



Notes: Ghea Brass bulkhead (or 35g)

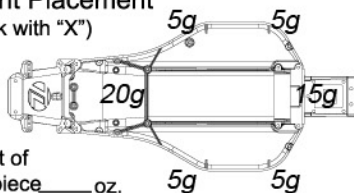
## Rear Suspension

Toe: Pivote: -3 degree - Hub: 0 degree  
 Pivot Support: 2 degree, Antisquat: None  
 Ride Height: 23 mm  
 Camber: -1 degree  
 Rear Hub Spacing: Long wheelbase  
 Drive Shafts/Outdrives: Universal steel / steel  
 Sway Bar: None  
 Oil: 25 wt  
 Piston: Orange (55) Other: \_\_\_\_\_  
 Spring: Yellow 2.0 (no coils cut)  
 Limiters: Inside: None - Outside: None - Unscrewed: 0 turns  
 Camber Link: 7 - E Ballstud washers: 0.09  
 Shock Location: 3 - Outside  
 VLA: long  
 Wing Position/Mount: Standard / Bottom  
 Body & Wing Type: TripleX-CR - A8110 High Down force  
 Battery Position: Forward



Notes: Rear shocks changed due to the back of the car slapping down after jumps, worked well and was able to attack jumps more. The following hasn't been seen before now as this was the first completely dry meeting of the year

Weight Placement (Mark with "X")



Weight of each piece \_\_\_\_\_ oz.

Tires: Type Compound Insert Additive Motor: 7.5t Losi  
 Front: Schumacher Mini Spike green Losi fir Spur: 78 T  
 Rear: Schumacher Mini Spike green Mr O Blue Pinon: 26  
 Notes: Weight at the front there is 5g stuck to each side of the servo and 2x5g in the tiangle pod

