Image: State of the state					:: Date: 08/07/11 rc.org.au)	
Setup Sheet for Team /	Associated's B4.1			Reset Forms	Rev.	
:: Front End		:: Rear	• End			
12300	camber: <mark>-1 deg</mark>		123	• camber: <u>-1 de</u>	9	
122 washers:			washers 2	anti-squat std 0 other		
toe: <u>1.5deg out</u> ride h pump steer spacer: 2 x 0.03"		std 0° r 0.5° 1° wheel	base	e height: 24mm anti-roll none black (so silver (m gold (ha	oft) 🛛 ned) 🗖	
: Front Shocks		:: Rear	Shocks			
spring: <u>Brown</u> shock oil: ^{35 wt AE (3mm rebound)}	piston: <u>#1</u> limiter: <u>2×0.03"</u>	_ spring _ shock	: <u>Green</u> oil: <u>27.5 AE (3mm rebo</u>	piston: <u>#2</u> ^{Jund)} limiter: <u>2</u>		
pinion: ²⁴ spur gear: ⁷⁵ batteries: ^{IB5000 40C (+ 40g ballast underneath). Total weight = 310g. battery placement: ^{Middle}}		_ thrott _ thrott _ esc: <u>№</u> _ initial b	radio: <u>KO Propo EX-10 Helios 2.4Ghz</u> throttle / brake epa: <u>100% / 60%</u> throttle / brake expo : <u>-15% / 0%</u> esc: <u>Novak Kinetic v1.4.1</u> throttle profile: <u>Linear</u> initial brake: <u>18%</u> drag brake: <u>18%</u> servo: <u>KO PDS 2363</u> steering expo: <u>0%</u>			
body: <u>JConcepts B4.1 Punisher</u>	V-Wing with 1/2" Lip	gear d	erential	uid: 🗖		
:: Front Tires	JConcepts Double Dee Custom cut down (Wet) een (DD)	tire: (cc compo insert		oleshot		
:: Race and Vehicle C	omments		:: Track Info			
qualify: 1 main: A finish: 2 tq: tq: Image: Comments: Ballast: 10g front of servo, 10g front bulkhead. No weight at rear. Novak Kinetic settings: Linear throttle / brake, 13.8kHz drive freq, 2.25kHz brake freq. 0% Min drive, 2% deadband, Timing advance OFF, Current Limiter OFF. 2deg anti-squat, 0deg plastic rear hubs. Black ballstud mounted in front hole on steering All plastic parts. Car balance very good.			traction: h soft dirt: dusty: o	wet (slippery) to wet (marbled, high] ;t: []	

:: For more setups, visit www.RC10.com and click on "Racing" then "Setups"